Mechanical Engineering Technology GENERAL PRESENTATION



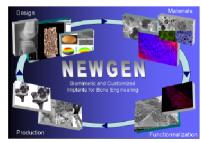
- ✓ Complete denomination: KU Leuven, Department of Mechanical Engineering, Mechanical Engineering Technology, campus Geel
- ✓ Location (city, country): 2440 Geel, Belgium
- ✓ Coordinator: Luc Labey
- ✓ Contact person in NEWGEN: Luc Labey
- ✓ Working Group involvment: WG2 and WG4
- ✓ Staff: Luc Labey
- ✓ Research topics: orthopaedic implants and (external) assistive devices and their mechanical interaction with the human body

✓ Researchers expertises: in vivo 3D motion capture, in vitro

testing with joint simulators

KU Leuven,

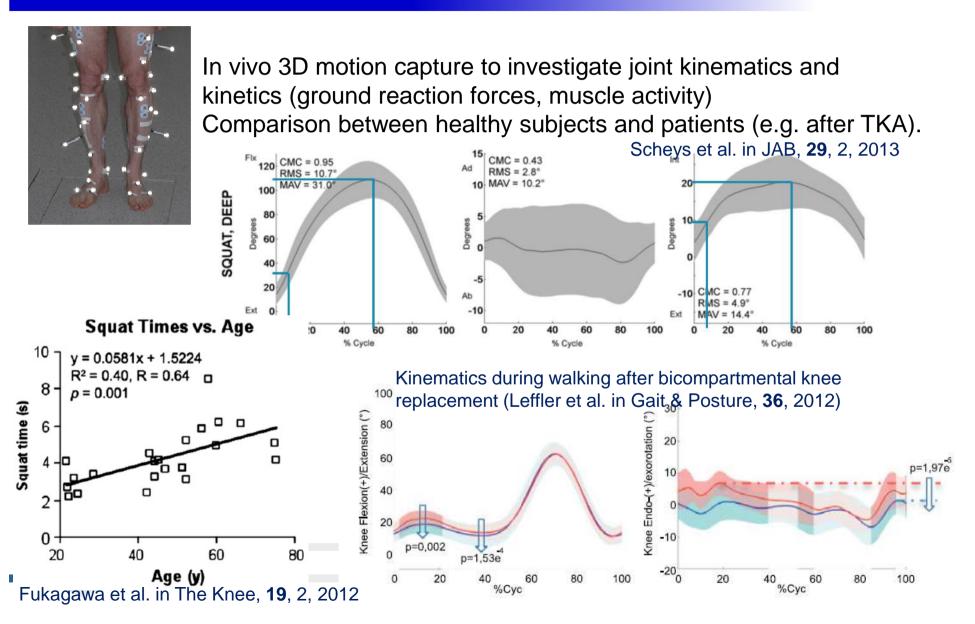
Mechanical engineering technology, campus Geel Kleinhoefstraat 4 2440 Geel - BELGIUM



COST Action MP130

Mechanical Engineering Technology BIOMECHANICS OF ASSISTIVE DEVICES





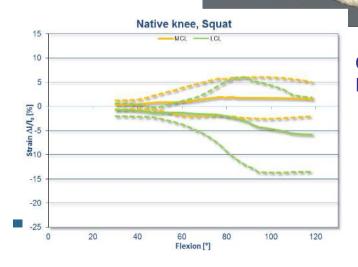
Mechanical Engineering Technology BIOMECHANICS OF ASSISTIVE DEVICES



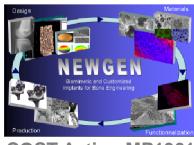


In vitro knee joint simulator to investigate joint kinematics and kinetics (tissue strains, joint contact force and pressure distribution) Comparison between native cadaver knee and the same knee after surgery.





Collateral ligament strains during squatting, Delport et al. in KSSTA, **23**, 8, 2015



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Mechanical Engineering Technology BIOMECHANICS OF ASSISTIVE DEVICES

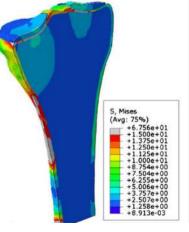


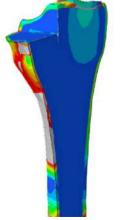
In silico simulation to investigate joint kinematics and kinetics (stress and strain in tissues)

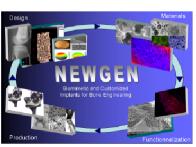
Comparison between native average knee and the same knee after surgery (incl. surgical error).

Knee kinematics after TKA

Bone stresses after UKA, Innocenti et al. in J Arthroj 29, 7, 2014







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Mechanical Engineering Technology FACILITIES



In vivo motion and shape measurements (in collaboration with Mobilab and BMe)



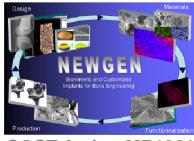
Vialux, 4D scanner



3D motion capture and gait analysis facilities



Diers, dynamic spine and posture analysis



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Mechanical Engineering Technology FACILITIES





In vitro kinematics and kinetics measurements (in collaboration with <u>Mobilab</u> and <u>BMe</u>)

Knee joint simulator

Foot-ankle simulator





Robotic gait simulator

